

New Modalities for Access Control Logics: Permission, Control and Ratification

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Abstract. We present a new modal access control logic, ACL^+ , to specify, reason about and enforce access control policies. The logic includes new modalities for permission, control, and ratification to overcome some limits of current access control logics. We present a Hilbert-style proof system for ACL^+ and a sound and complete Kripke semantics for it. We exploit the Kripke semantics to define $Seq-ACL^+$: a sound, complete and cut-free sequent calculus for ACL^+ , implying that ACL^+ is at least semi-decidable. We point at a Prolog implementation of $Seq-ACL^+$ and discuss possible extensions of ACL^+ with axioms for subordination between principals.

1 Introduction

Logic plays a prominent role in the specification, reasoning and enforcement of access control policies in distributed systems. In the last two decades, several logic-based models have been proposed for access control policies, each with its own primitives, semantics and, in some cases, specific application domains (see [1,3] and [7] for surveys). The great variety (and complexity) of such systems makes it difficult to integrate, compare and objectively evaluate them. As is evident from recent research in access control [2,8,11,14,17], modal logic is a powerful framework to study expressiveness, complexity and semantics of access control logics. Although modal logic has proved useful for theoretical study of access control, it is not widely used in practice to enforce authorization policies (some notable exceptions are [5,6,13,21,22]).

The main reason for this gap is that although several epistemic modalities (e.g., says [18], said and knows [17]) have been studied in the context of access control, key access control concepts like permission, control or trust are not first-class citizens of modal access control languages and must be defined using epistemic modalities. This creates implicit relationships between the concepts and possibly leads to security risks (see [2] for some examples).

In this paper, we take a step towards addressing this shortcoming by proposing a constructive modal logic, ACL^+ , which extends a standard access control logic with new connectives for permission, control and trust on principals' statements, and admits a semi-decidable calculus. We start by presenting a brief outline of the methodology of access control through logics in Section 2, and a specific connective says [18] that is central to almost all access control logics. In Section 3 we point at three shortcomings of says-based access control logics that, in our opinion, limit their applicability in practical

scenarios, thus motivating the need for the new modalities. In Section 4 we present the new modalities, their axioms and inference rules in a Hilbert-style calculus for ACL^+ . Moreover, we show through examples how ACL^+ avoids the shortcomings reported in Section 3.

Section 5 presents sound and complete Kripke semantics for ACL^+ . Kripke semantics, although useful for establishing several metatheorems of access control logics, are not operational and cannot be used directly in algorithms to reason about authorization. Accordingly, in Section 6 we present Seq-ACL^+ , a sound, complete and cut-free sequent calculus for ACL^+ and then impose termination conditions on the sequent calculus that are derived from the Kripke semantics. We conjecture that the termination conditions do not lead to loss of completeness and point the reader to a working implementation of the calculus in Prolog.¹ In Section 7 we present extensions of ACL^+ with axioms that force subordination between principals. Section 8 discusses briefly some related work and Section 9 concludes the paper. A full version of the paper with proofs of theorems and the Prolog implementation of ACL^+ are available from the authors' homepages.

2 Distributed Access Control Model

We consider a decentralized model of access control, where policy information is distributed among several principals. Principals support policy statements and credentials by writing them in certificates signed with their respective private keys. Since policy statements and credentials may be complex, and may assert facts conditional upon statements of other principals, formal logic is a natural choice to model policies. If principal A supports policy (or credential) φ , this is represented in the logic as the formula $A \text{ says } \varphi$ [18]. Technically, $A \text{ says } \bullet$ is a family of principal-indexed modalities that has been included in several access control logics, albeit with slightly varying semantic interpretations.

An access is authorized (justified) if and only if it is entailed by available policy statements and credentials. The question of authorizing an access φ for principal A from a policy Γ can be cast formally as follows: Is it the case that Γ and $A \text{ says } \varphi$ entail φ ? Or, in symbolic notation, is there a formal proof that $\Gamma, A \text{ says } \varphi \vdash \varphi$?

Example 1. Consider the following policy:

1. If the *Admin* says that *file1* can be read, then this must be the case.
2. *Admin* trusts *Bob* to decide whether or not *file1* can be read.

In a propositional logic enriched with the *says* modality, we can express the above policy as follows [2]:

1. $(\text{Admin says read_file1}) \rightarrow \text{read_file1}$
2. $\text{Admin says } ((\text{Bob says read_file1}) \rightarrow \text{read_file1})$

¹ In an earlier version of this paper we mentioned a proof of decidability of ACL^+ , but subsequently we found a mistake in the proof that we have been unable to fix. However, we still believe that ACL^+ is decidable, hence the conjecture.

Further, *Bob* asking to read *file1* can be represented as *Bob* says *read_file1*. The reference monitor may authorize *Bob* on this request if and only if

$$(1), (2), \textit{Bob} \textit{ says read_file1} \vdash \textit{read_file1}$$

In most access control logics, the above entailment has a proof, so *Bob* will be able to read *file1*. We re-emphasize that the notion of authorization w.r.t. to a submitted request corresponds to the formal notion of derivability of the requested access from the available policy.

3 Limits of Access Control Logics: Permissions, Control and Information Flow

In this Section we point out three issues that, in our opinion, create a gap between existing work on logic-based approaches to access control as outlined above, and their deployment in practice. We call the first issue the problem of *implicit permissions*: If an action φ is entailed by a policy Γ , then *any* principal is authorized to perform it. The second issue concerns a logical separation of permission to perform an action from the ability to *control* the action, which also includes the permission to delegate the control further. The third issue is concerned with a fine-grained distinction between the *flow of information* (policy statements) from one principal to another, and its *acceptance* by the receiving principal or, in other words, the issue of separating (in the logic) hearsay from trust in the hearsay. We explain these issues one by one, and then present our proposal to address the issues by introducing new modalities into the logic.

Issue 1: Implicit permissions

The standard definition of permission through entailment presented in Section 2 says that a principal A can perform action φ if from the prevailing policy Γ and A says φ , φ can be established. However, this creates a problem in practice: Once enough credentials exist to authorize an access for some principal, any principal is permitted the same access by the standard definition. For instance, in our earlier example, after *Bob* has created the credential *Bob* says *read_file1*, any principal A will be authorized to read *file1*. This is because the existence of a proof of $\Gamma, \textit{Bob} \textit{ says read_file1} \vdash \textit{read_file1}$ implies, by the law of weakening in the logic, that $\Gamma, \textit{Bob} \textit{ says read_file1}, A \textit{ says read_file1} \vdash \textit{read_file1}$ is also provable for any principal A .

The problem here is that the formula asserting the authorization — *read_file1* — does not include the identity of the principal who is authorized access. We propose to resolve this problem by introducing an explicit, principal-indexed modality for permissions, which we write $\mathbf{P}_A\varphi$ (Section 4). With this modality, policy Γ authorizes principal A to perform action φ iff $\Gamma \vdash \mathbf{P}_A\varphi$. By explicitly listing the principal authorized in the conclusion, we eliminate the problem of implicit permissions.

An alternate, related solution, not considered here, but often used in first-order logics for access control, is to treat the permission (e.g., *read_file1*) as a relation over principals. Instead of writing *read_file1* we could write *read_file1(A)* to mean that principal A is authorized to read *file1*. However, since we are interested in implementing the logic, we avoid first-order logic.

Issue 2: Control or Delegatable Permissions

Often in access control, it is desirable to give an individual a permission and also the power to further delegate the permission. To this end we propose a new modality $\mathbf{C}_A\varphi$, read “ A controls φ ”. The key axioms governing $\mathbf{C}_A\varphi$ are:

$$\begin{aligned} \vdash \mathbf{C}_A\varphi \rightarrow \mathbf{P}_A\varphi & \quad (\text{C2P}) \\ \vdash (\mathbf{C}_A\varphi \wedge (A \text{ says } \mathbf{C}_B\varphi)) \rightarrow \mathbf{C}_B\varphi & \quad (\text{del-C}) \end{aligned}$$

The first axiom means that if principal A controls φ , then it is also permitted φ . This axiom relates control to permission and makes $\mathbf{C}_A\varphi$ strictly stronger than $\mathbf{P}_A\varphi$. The second axiom allows principal A , who controls φ , to delegate this control to a principal B simply by asserting this fact. This ability to delegate further distinguishes $\mathbf{C}_A\varphi$ from $\mathbf{P}_A\varphi$.

It is desirable that $(\mathbf{C}_A\varphi_1 \wedge \mathbf{C}_A\varphi_2) \rightarrow \mathbf{C}_A(\varphi_1 \wedge \varphi_2)$. For instance, if A has control over the deletion of files 1 and 2 individually, it should also have control over the deletion of the two files together, thus allowing it to delegate control over deletion of both files at once. A similar property for permissions may be harmful. For instance, if file 2 is the backup of file 1, we may not want to permit their simultaneous deletion ($\mathbf{P}_A(\varphi_1 \wedge \varphi_2)$), even if we allow their deletion individually ($\mathbf{P}_A\varphi_1 \wedge \mathbf{P}_A\varphi_2$). Formally, this difference is manifest in different logical treatments of the two modalities: while \mathbf{C}_A is a normal *necessitation* modality, \mathbf{P}_A is a *possibility* modality (see Section 4 for details).

Issue 3: Information Flow vs Acceptance

Besides the use of the modality \mathbf{C}_A , authority can also be delegated from one principal to another by nesting the says modality, as in the following statement from Example 1, which delegates the formula *read_file1* from principal *Admin* to principal *Bob*:

$$2. \text{ Admin says } ((\text{Bob says } \text{read_file1}) \rightarrow \text{read_file1})$$

Intuitively, we expect (as in Example 1) that this formula together with *Bob says read_file1* should imply that *Admin says read_file1*. However, performing this inference requires us to infer from *Bob says read_file1* that *Admin says Bob says read_file1*. To allow for this inference, most authorization logics include the following axiom, or a stronger axiom that implies it (this axiom was proposed by Abadi [1]):

$$A \text{ says } \varphi \rightarrow B \text{ says } (A \text{ says } \varphi) \quad (\text{I-SS})$$

However, this axiom also allows unwanted statements to flow from one principal to another. Here is an example. Suppose *Admin* delegates to *Bob* the authority to *read_file1* through statement (2), under the conception that *Bob* will only allow *read_file1* under reasonable conditions. However, *Bob*, either mistakenly or maliciously, adds the following rule:

$$\text{Bob says } (\text{bad_condition} \rightarrow \text{read_file1})$$

where *bad_condition* means that a certain bad condition (for reading *file1*) holds. Now, using the statements above and (I-SS), *Bob says bad_condition* implies that *Admin says read_file1*, which is undesirable.

The problem here is that the logic, so far, does not provide a construct to allow *Admin* to represent in statement (2) that it actually *trusts* the assumption (*Bob* says *read_file1*). We propose to rectify this situation by including the construct *A* ratified φ , which means that *A* says φ and that this statement is trusted by the principal in the enclosing scope. With this construct, *Admin* can revise its statement to say that:

2a. *Admin* says $((\text{Bob ratified } read_file1) \rightarrow read_file1)$

If *Bob* merely says *read_file1*, it will imply *Admin* says *Bob* says *read_file1*, but not *Admin* says *Bob* ratified *read_file1*, and not allow for the deduction of *Admin* says *read_file1*. To allow for the latter, *Admin* must make explicit rules to convert *Bob*'s statements to ratified statements, e.g., it may add the following two rules:

3. *Admin* says $((\text{Bob says } good_condition) \rightarrow (\text{Bob ratified } good_condition))$
4. *Admin* says $((\text{Bob says } (good_condition \rightarrow read_file1)) \rightarrow (\text{Bob ratified } (good_condition \rightarrow read_file1)))$

thus allowing deduction of *Admin* says *read_file1* from the statements *Bob* says $(good_condition \rightarrow read_file1)$ and *Bob* says *good_condition*, but not from *Bob* says $(bad_condition \rightarrow read_file1)$ and *Bob* says *bad_condition*. The formal rules that allow these deductions and a more detailed example of the use of ratification are presented in Section 4.

4 The New Modalities

In this section we formally describe ACL^+ , our access control logic with the modalities P_A , C_A and *A* ratified \bullet . To summarize,

1. Permission and control can be represented directly in ACL^+ using the modalities $P_A\varphi$ (principal *A* is authorized (permitted) φ) and $C_A\varphi$ (principal *A* controls φ).
2. ACL^+ contains the operator *A* ratified φ , which means that principal *A* states φ and this statement has been ratified (or, is trusted) by the principal in whose context the formula is interpreted.

We introduce ACL^+ piecewise, starting with a simple access control logic containing the modality says defined by the following rules and axioms (φ and ψ denote logical formulas):

All axioms of intuitionistic propositional logic	(IPC)
$\frac{\vdash \varphi \quad \vdash \varphi \rightarrow \psi}{\vdash \psi}$	(MP)
$\frac{\vdash \varphi}{\vdash A \text{ says } \varphi}$	(nec-S)
$\vdash (A \text{ says } (\varphi \rightarrow \psi)) \rightarrow (A \text{ says } \varphi) \rightarrow (A \text{ says } \psi)$	(K-S)
$\vdash A \text{ says } \varphi \rightarrow B \text{ says } (A \text{ says } \varphi)$	(I-SS)

We note that our logic is intuitionistic (constructive). The use of intuitionistic logic for access control has been motivated in prior work [12]; briefly, constructivism disallows proofs by contradiction, thus eliminating authorization if it is merely not denied. Axioms (nec-S) and (K-S) express that says is a normal necessitation modality and are standard in access control literature.

4.1 Permission and Control

To this basic logic we add the modalities \mathbf{P}_A and \mathbf{C}_A , characterized by the following rules and axioms:

$$\begin{array}{l}
\frac{\vdash \varphi}{\vdash \mathbf{C}_A \varphi} \quad (\text{nec-C}) \\
\vdash \mathbf{C}_A(\varphi \rightarrow \psi) \rightarrow (\mathbf{C}_A \varphi \rightarrow \mathbf{C}_A \psi) \quad (\text{C-Deduce}) \\
\vdash \mathbf{C}_A \varphi \rightarrow \mathbf{P}_A \varphi \quad (\text{C2P}) \\
\vdash \mathbf{P}_A(\varphi \vee \psi) \rightarrow \mathbf{P}_A \varphi \vee \mathbf{P}_A \psi \quad (\text{or-P}) \\
\vdash (\mathbf{C}_A \varphi \wedge (A \text{ says } \mathbf{C}_B \varphi)) \rightarrow \mathbf{C}_B \varphi \quad (\text{del-C})
\end{array}$$

Axiom (C-Deduce) expresses that control is closed under logical deduction while rule (nec-C) means that all valid formulas of the logic are controlled by every principal A . Together, (nec-C) and (C-Deduce) make \mathbf{C}_A a normal necessitation modality (similar to \Box in standard modal logics). As motivated in Section 3, we model permission with a possibility modality, i.e., it is not closed under logical consequence, but we require it to distribute over disjunction (or-P). Axiom (C2P) relates the notion of control to that of permission and reads: “If principal A controls φ , then it is authorized (permitted) on φ ”. This implies that control of a formula is stronger than permission on the formula. Axiom (del-C) allows a principal A in control of φ to delegate that control to another principal B (see Example 2).

Definition 1 (Authorization). *Given a policy Γ , we say that A is authorized on access φ if and only if $\Gamma \vdash \mathbf{P}_A \varphi$.*

Example 2. The policy of Example 1 can be re-represented with the new modalities as follows

- (1) $\mathbf{C}_{Admin}(read_file1)$
- (2) $Admin \text{ says } (\mathbf{C}_{Bob}(read_file1))$

From (del-C), (MP) and (C2P) we can prove that Bob is authorized to read $file1$, i.e., $(1), (2) \vdash \mathbf{P}_{Bob}(read_file1)$.

Example 3. A principal can selectively delegate privileges it controls to other principals. Consider a policy in which A controls the deletion of files 1 and 2. A can delegate to B the authority to delete file 1 only by asserting that B controls it. Formally,

$$\mathbf{C}_A(delete_file1 \wedge delete_file2), A \text{ says } (\mathbf{C}_B(delete_file1)) \vdash \mathbf{C}_B(delete_file1)$$

Proof. From the assumption $\mathbf{C}_A(delete_file1 \wedge delete_file2)$ infer using (nec-C) and (C-deduce) that $\mathbf{C}_A(delete_file1)$. $\mathbf{C}_B(delete_file1)$ follows using (del-C) and the assumption $A \text{ says } (\mathbf{C}_B(delete_file1))$.

4.2 The Modality (A ratified φ)

Next, we add to our logic the modality A ratified φ , which means not only that A says φ , but also that the latter has been checked, ratified, or is trusted by the principal in whose scope it occurs (Section 3). For instance, the formula B says (A ratified φ) means that: “ A says φ and B ratified (trusts) this statement”.

Like \mathbf{C}_A and A says \bullet , we model A ratified \bullet as a normal modality:

$$\frac{\vdash \varphi}{\vdash A \text{ ratified } \varphi} \quad (\text{nec-R})$$

$$\vdash (A \text{ ratified } (\varphi \rightarrow \psi)) \rightarrow (A \text{ ratified } \varphi) \rightarrow (A \text{ ratified } \psi) \quad (\text{K-R})$$

Further, the modality A ratified φ implies A says φ , but the converse is not true in general:

$$\vdash (A \text{ ratified } \varphi) \rightarrow (A \text{ says } \varphi) \quad (\text{RS})$$

The axiom (RS) makes A ratified φ stronger than A says φ . Statement φ directly signed by a principal can be taken as an evidence of A says φ , not A ratified φ . (I-SS) and (RS) together imply that:

$$\vdash (A \text{ ratified } \varphi) \rightarrow B \text{ says } A \text{ says } \varphi$$

but it is not possible to derive in general that

$$\vdash (A \text{ says } \varphi) \rightarrow B \text{ says } A \text{ ratified } \varphi$$

which would be unjustified because if A says φ , then B has not necessarily ratified it.

Example 4. The purpose of introducing the modality A ratified \bullet is to allow a principal control over what statements and proofs of another principal it will admit as trusted. Assume that a hospital administrator PA controls access to sensitive patient records. The main policy is that “a doctor has access to all patient records” and the determination of who constitutes a doctor comes from the principal HR , representing the human resources database. Let $\mathbf{C}_A(\text{access_records})$ mean that principal A has control over the access to patient records and $\text{isDoctor_}A$ mean that A is a doctor. Let \mathcal{P} be the set of all relevant principals. The main policy can be encoded as the formula²:

$$PA \text{ says } \bigwedge_{A \in \mathcal{P}} [(HR \text{ ratified } \text{isDoctor_}A) \rightarrow (\mathbf{C}_A(\text{access_records}))] \quad (\text{P1})$$

Observe that we are using $(HR \text{ ratified } \dots)$ inside the policy instead of $(HR \text{ says } \dots)$ to ensure that consequences of the policy depend only on statements of HR that have been ratified by PA .

Now, PA can choose to trust the policies of HR selectively. For instance, if PA trusts all deductions of the form $\text{isDoctor_}A$ that HR may make, it can have the policy:

$$PA \text{ says } \bigwedge_{A \in \mathcal{P}} ((HR \text{ says } \text{isDoctor_}A) \rightarrow (HR \text{ ratified } \text{isDoctor_}A)) \quad (\text{P2})$$

² Because we are using a propositional language, we assume principals to range over a *finite* set \mathcal{P} . Accordingly, $\bigwedge_{A \in \mathcal{P}} \varphi$ reads “For all principals A in \mathcal{P} , φ holds”.

Then, for any principal A , we have that

$$(P1), (P2), HR \text{ says } (isDoctor_A) \vdash PA \text{ says } C_A(access_records)$$

If, on the other hand, PA only trusts HR 's statements about two principals $Alice$ and Bob , it can selectively assert (in place of (P2)) that:

$$PA \text{ says } ((HR \text{ says } isDoctor_Alice) \rightarrow (HR \text{ ratified } isDoctor_Alice))$$

$$PA \text{ says } ((HR \text{ says } isDoctor_Bob) \rightarrow (HR \text{ ratified } isDoctor_Bob))$$

As a last illustration, suppose that the HR has two policies, one of which states that every administrator is a doctor and the other of which (mistakenly) states that every hospital employee is a doctor:

$$HR \text{ says } \bigwedge_{A \in \mathcal{P}} (isAdmin_A \rightarrow isDoctor_A) \quad (P3)$$

$$HR \text{ says } \bigwedge_{A \in \mathcal{P}} (isEmployee_A \rightarrow isDoctor_A) \quad (P4)$$

PA can choose to ratify the first of these, but not the second, by asserting in place of (P2) that:

$$PA \text{ says } ((HR \text{ says } \bigwedge_{A \in \mathcal{P}} (isAdmin_A \rightarrow isDoctor_A)) \rightarrow (HR \text{ ratified } \bigwedge_{A \in \mathcal{P}} (isAdmin_A \rightarrow isDoctor_A))) \quad (P5)$$

$$PA \text{ says } \bigwedge_{A \in \mathcal{P}} ((HR \text{ says } isAdmin_A) \rightarrow (HR \text{ ratified } isAdmin_A)) \quad (P6)$$

Suppose that HR says $isAdmin_Alice$. Then, we can deduce PA says $C_{Alice}(access_records)$ from (P1), (P3), (P5) and (P6) as follows:

1. From (P3) and (I-SS), deduce that

$$PA \text{ says } (HR \text{ says } (\bigwedge_{A \in \mathcal{P}} (isAdmin_A \rightarrow isDoctor_A)))$$

2. From (1), (K-S) and (P5) deduce that

$$PA \text{ says } (HR \text{ ratified } (\bigwedge_{A \in \mathcal{P}} (isAdmin_A \rightarrow isDoctor_A)))$$

3. From $(HR \text{ says } isAdmin_Alice)$ and (I-SS) deduce that $(PA \text{ says } HR \text{ says } isAdmin_Alice)$
4. From (3), (K-S) and (P6) deduce that $(PA \text{ says } HR \text{ ratified } isAdmin_Alice)$
5. From (2), (4), (K-S), and (K-R) deduce that $(PA \text{ says } HR \text{ ratified } isDoctor_Alice)$
6. From (5), (P1), and (K-S) deduce that $(PA \text{ says } C_{Alice}(access_records))$

If we replace the assumption $(HR \text{ says } isAdmin_Alice)$ with the assumption $(HR \text{ says } isEmployee_Alice)$, then we cannot deduce $(PA \text{ says } (C_{Alice}(access_records)))$ because we cannot deduce (5) above. In place of (5), we can deduce only the weaker statement $(PA \text{ says } (HR \text{ says } isDoctor_Alice))$, which does not imply $(PA \text{ says } C_{Alice}(access_records))$ in our theory.

5 Semantics

In this section, we define sound and complete semantics for ACL^+ . Our semantics uses graph-based structures called Kripke models, that are standard in modal logic. The technical challenge here, as for every modal logic, lies in identifying a suitable class of Kripke structures that correspond exactly to the calculus of Section 4. Although Kripke semantics are not necessarily intuitive, they lead directly to a proof theory for the logic, a semi-decidability result for it and an implementation of the proof theory (Section 6).

Definition 2. *An intuitionistic model, \mathcal{M} , of ACL^+ is a tuple*

$$(W, \leq, \{S_A\}_{A \in \mathcal{P}}, \{C_A\}_{A \in \mathcal{P}}, \{R_A\}_{A \in \mathcal{P}}, \{P_A\}_{A \in \mathcal{P}}, h)$$

where

- \mathcal{P} is a set of principals.
- (W, \leq) is a preorder, where elements of W are called states or worlds, and \leq is a binary relation over W which satisfies the following conditions
 - $\forall x. (x \leq x)$ (refl)
 - $\forall x, y, z. ((x \leq y) \wedge (y \leq z) \rightarrow (x \leq z))$ (trans)
- S_A, C_A, R_A and P_A are binary relations on W that satisfy the following conditions:
 - $\forall x, y, z, w. (((x \leq y) \wedge (yS_Az) \wedge (z \leq w)) \rightarrow (xS_Aw))$ (mon-S)
 - $\forall x, y, z, w. (((x \leq y) \wedge (yC_Az) \wedge (z \leq w)) \rightarrow (xC_Aw))$ (mon-C)
 - $\forall x, y, z, w. (((x \leq y) \wedge (yR_Az) \wedge (z \leq w)) \rightarrow (xR_Aw))$ (mon-R)
 - $\forall x, y, z, w. (((x \leq y) \wedge (zP_Ay) \wedge (z \leq w)) \rightarrow (wP_Ax))$ (mon-P)
- h is an assignment which, for each atom q , assigns the subset of worlds $h(q) \subseteq W$ where q holds. Moreover, we require h to be monotone w.r.t. \leq , i.e., if $x \in h(q)$ and $x \leq y$ then $y \in h(q)$.

Conditions above ensure monotonicity of the logic (Lemma 1), which is a standard property of Kripke semantics for constructive logics. Moreover, to force ACL^+ models to admit the axioms (I-SS), (C2P), (del-C) and (RS) we require the following to hold for any two principals A and B .

$$\begin{aligned} \forall x, y, z. (((xS_By) \wedge (yS_Az)) \rightarrow (xS_Az)) & \quad \text{(s-I-SS)} \\ \forall x \exists y. (xC_Ay \wedge xP_Ay) & \quad \text{(s-C2P)} \\ \forall x, y. ((xC_By) \rightarrow ((xC_Ay) \vee \exists z((xS_Az) \wedge (zC_By)))) & \quad \text{(s-del-C)} \\ \forall x, y. ((xS_Ay) \rightarrow (xR_Ay)) & \quad \text{(s-RS)} \end{aligned}$$

An interpretation for the logic is a pair \mathcal{M}, t where \mathcal{M} is a model and t is a world in \mathcal{M} .

Definition 3 (Satisfaction Relation). *The satisfaction relation “ \models ” between interpretations and formulae of the logic is defined below. (The letter q denotes an atomic formula.)*

- $\mathcal{M}, t \models q$ iff $t \in h(q)$
- $\mathcal{M}, t \not\models \perp$

- $\mathcal{M}, t \models \varphi \vee \psi$ iff $\mathcal{M}, t \models \varphi$ or $\mathcal{M}, t \models \psi$
- $\mathcal{M}, t \models \varphi \wedge \psi$ iff $\mathcal{M}, t \models \varphi$ and $\mathcal{M}, t \models \psi$
- $\mathcal{M}, t \models \varphi \rightarrow \psi$ iff for all $s, t \leq s$ and $\mathcal{M}, s \models \varphi$ imply $\mathcal{M}, s \models \psi$
- $\mathcal{M}, t \models \neg\varphi$ iff for all $s, t \leq s$ implies $\mathcal{M}, t \not\models \varphi$
- $\mathcal{M}, t \models A \text{ says } \varphi$ iff for all s such that $tS_A s$ we have $\mathcal{M}, s \models \varphi$
- $\mathcal{M}, t \models C_A\varphi$ iff for all s such that $tC_A s$ we have $\mathcal{M}, s \models \varphi$
- $\mathcal{M}, t \models A \text{ ratified } \varphi$ iff for all s such that $tR_A s$ we have $\mathcal{M}, s \models \varphi$
- $\mathcal{M}, t \models P_A\varphi$ iff there exists an s such that $tP_A s$ and $\mathcal{M}, s \models \varphi$

Lemma 1 (Monotonicity). *For any formula φ and any interpretation \mathcal{M}, t , if $\mathcal{M}, t \models \varphi$ and $t \leq s$ then $\mathcal{M}, s \models \varphi$.*

We say that $\mathcal{M} \models \varphi$ if for all $t \in \mathcal{M}$, it is the case that $\mathcal{M}, t \models \varphi$. Further, $\Gamma \models \varphi$ if for every intuitionistic model \mathcal{M} , $\mathcal{M} \models \Gamma$ implies $\mathcal{M} \models \varphi$.

Theorem 1 (Soundness). *If $\vdash \varphi$ then $\models \varphi$*

Theorem 2 (Completeness). *If $\Gamma \models \varphi$ then $\Gamma \vdash \varphi$*

We note that the conditions (s-I-SS), (s-C2P), (s-del-C) and (s-RS) are *canonical* for the axioms (I-SS), (C2P), (del-C) and (RS), respectively, i.e., a logic with any subset of these axioms is sound and complete with respect to models that satisfy the conditions corresponding to the chosen axioms.

6 A Semantics-Based Calculus for ACL^+

In this section we briefly present Seq-ACL^+ , a sound, complete and cut-free sequent calculus for ACL^+ . The calculus is inspired by the work of Negri [19]³ and follows the so-called labeled approach [4,20], which directly uses the Kripke semantics. The use of labeled sequent calculi for access control is relatively new and has been introduced in [15,16] to define proof theory of a specific says-based access control logic. Our sequent calculus directly leads to a semi-decision procedure for the logic ACL^+ .

Seq-ACL^+ manipulates two types of labeled formulas:

1. *World formulas*, denoted by $x : \varphi$, where x is a world and φ is a formula of ACL^+ , intuitively meaning that φ holds in world x .
2. *Transition formulas* representing semantic accessibility relationships. These formulas have one of the forms $xS_A y, xC_A y, xR_A y, xP_A y$ and $x \leq y$.

A sequent is a tuple $\langle \Sigma, \mathbb{M}, \Gamma, \Delta \rangle$, usually written $\Sigma; \mathbb{M}; \Gamma \Rightarrow \Delta$ where \mathbb{M}, Γ and Δ are multisets of labeled formulas and Σ is the set of labels (worlds) appearing in the rest of the sequent. Intuitively, the sequent $\Sigma; \mathbb{M}; \Gamma \Rightarrow \Delta$ means that “every model which satisfies all labeled formulas of $\Gamma \cup \mathbb{M}$ satisfies at least one labeled formula in Δ ”. This is made precise by the notion of *validity* in the following definition.

³ In particular, proofs of metatheorems about Seq-ACL^+ use methods developed in [19].

Axiom Rules

$$\frac{}{\Sigma; \mathbb{M}, x \leq y; \Gamma, x : p \Rightarrow y : p, \Delta} \text{init} \quad \frac{}{\Sigma; \mathbb{M}; \Gamma, x : \perp \Rightarrow \Delta} \perp\text{L} \quad \frac{}{\Sigma; \mathbb{M}; \Gamma \Rightarrow x : \top, \Delta} \top\text{R}$$

Logical Rules

$$\frac{\Sigma; \mathbb{M}; \Gamma \Rightarrow_{\mathcal{T}} x : \alpha, \Delta \quad \Sigma; \mathbb{M}; \Gamma \Rightarrow_{\mathcal{T}} x : \beta, \Delta}{\Sigma; \mathbb{M}; \Gamma \Rightarrow_{\mathcal{T}} x : \alpha \wedge \beta, \Delta} \wedge\text{R} \quad \frac{\Sigma; \mathbb{M}; \Gamma, x : \alpha, x : \beta \Rightarrow_{\mathcal{T}} \Delta}{\Sigma; \mathbb{M}; \Gamma, x : \alpha \wedge \beta \Rightarrow_{\mathcal{T}} \Delta} \wedge\text{L}$$

$$\frac{\Sigma; \mathbb{M}; \Gamma \Rightarrow_{\mathcal{T}} x : \alpha, x : \beta, \Delta}{\Sigma; \mathbb{M}; \Gamma \Rightarrow_{\mathcal{T}} x : \alpha \vee \beta, \Delta} \vee\text{R} \quad \frac{\Sigma; \mathbb{M}; \Gamma, x : \alpha \Rightarrow_{\mathcal{T}} \Delta \quad \Sigma; \mathbb{M}; \Gamma, x : \beta \Rightarrow_{\mathcal{T}} \Delta}{\Sigma; \mathbb{M}; \Gamma, x : \alpha \vee \beta \Rightarrow_{\mathcal{T}} \Delta} \vee\text{L}$$

$$\frac{\Sigma; \mathbb{M}, x \leq y; \Gamma, x : \alpha \rightarrow \beta \Rightarrow_{\mathcal{T}} y : \alpha, \Delta \quad \Sigma; \mathbb{M}, x \leq y; \Gamma, x : \alpha \rightarrow \beta, y : \beta \Rightarrow_{\mathcal{T}} \Delta}{\Sigma; \mathbb{M}, x \leq y; \Gamma, x : \alpha \rightarrow \beta \Rightarrow \Delta} \rightarrow\text{L}$$

$$\frac{\Sigma, y; \mathbb{M}, x \leq y; \Gamma, y : \alpha \Rightarrow y : \beta, \Delta}{\Sigma; \mathbb{M}; \Gamma \Rightarrow x : \alpha \rightarrow \beta, \Delta} \rightarrow\text{R}_{y \text{ new}}$$

$$\frac{\Sigma; \mathbb{M}, xS_{Ay}; \Gamma, x : A \text{ says } \alpha, y : \alpha \Rightarrow \Delta}{\Sigma; \mathbb{M}, xS_{Ay}; \Gamma, x : A \text{ says } \alpha \Rightarrow \Delta} \text{says L} \quad \frac{\Sigma, y; \mathbb{M}, xS_{Ay}; \Gamma \Rightarrow_{\mathcal{T}} y : \alpha, \Delta}{\Sigma; \mathbb{M}; \Gamma \Rightarrow_{\mathcal{T}} x : A \text{ says } \alpha, \Delta} \text{says R}_{y \text{ new}}$$

$$\frac{\Sigma; \mathbb{M}, xC_{Ay}; \Gamma, x : \mathbf{C}_A \alpha, y : \alpha \Rightarrow \Delta}{\Sigma; \mathbb{M}, xC_{Ay}; \Gamma, x : \mathbf{C}_A \alpha \Rightarrow \Delta} \text{CL} \quad \frac{\Sigma, y; \mathbb{M}, xC_{Ay}; \Gamma \Rightarrow y : \alpha, \Delta}{\Sigma; \mathbb{M}; \Gamma \Rightarrow x : \mathbf{C}_A \alpha, \Delta} \text{CR}_{y \text{ new}}$$

$$\frac{\Sigma; \mathbb{M}, xR_{Ay}; \Gamma, x : A \text{ ratified } \alpha, y : \alpha \Rightarrow \Delta}{\Sigma; \mathbb{M}, xR_{Ay}; \Gamma, x : A \text{ ratified } \alpha \Rightarrow \Delta} \text{ratified L} \quad \frac{\Sigma, y; \mathbb{M}, xR_{Ay}; \Gamma \Rightarrow y : \alpha, \Delta}{\Sigma; \mathbb{M}; \Gamma \Rightarrow x : A \text{ ratified } \alpha, \Delta} \text{ratified R}_{y \text{ new}}$$

$$\frac{\Sigma; \mathbb{M}, xP_{Ay}; \Gamma \Rightarrow x : \mathbf{P}_A \alpha, y : \alpha, \Delta}{\Sigma; \mathbb{M}, xP_{Ay}; \Gamma \Rightarrow x : \mathbf{P}_A \alpha, \Delta} \text{PR} \quad \frac{\Sigma, y; \mathbb{M}, xP_{Ay}; \Gamma, y : \alpha \Rightarrow \Delta}{\Sigma; \mathbb{M}; \Gamma, x : \mathbf{P}_A \alpha \Rightarrow \Delta} \text{PL}_{y \text{ new}}$$

Semantical Rules

$$\frac{\Sigma; \mathbb{M}, x \leq y, yS_{Az}, z \leq w, xS_{Aw}; \Gamma \Rightarrow \Delta}{\Sigma; \mathbb{M}, x \leq y, yS_{Az}, z \leq w; \Gamma \Rightarrow \Delta} \text{mon-S} \quad \frac{\Sigma; \mathbb{M}, x \leq y, yC_{Az}, z \leq w, xC_{Aw}; \Gamma \Rightarrow \Delta}{\Sigma; \mathbb{M}, x \leq y, yC_{Az}, z \leq w; \Gamma \Rightarrow \Delta} \text{mon-C}$$

$$\frac{\Sigma; \mathbb{M}, x \leq y, yR_{Az}, z \leq w, xR_{Aw}; \Gamma \Rightarrow \Delta}{\Sigma; \mathbb{M}, x \leq y, yR_{Az}, z \leq w; \Gamma \Rightarrow \Delta} \text{mon-R} \quad \frac{\Sigma; \mathbb{M}, x \leq y, zP_{Ay}, z \leq w, wP_{Ax}; \Gamma \Rightarrow \Delta}{\Sigma; \mathbb{M}, x \leq y, zP_{Ay}, z \leq w; \Gamma \Rightarrow \Delta} \text{mon-P}$$

$$\frac{\Sigma; \mathbb{M}, x \leq x; \Gamma \Rightarrow \Delta}{\Sigma; \mathbb{M}; \Gamma \Rightarrow \Delta} \text{refl}_{x \in \Sigma} \quad \frac{\Sigma; \mathbb{M}, x \leq y, y \leq z, x \leq z; \Gamma \Rightarrow \Delta}{\Sigma; \mathbb{M}, x \leq y, y \leq z; \Gamma \Rightarrow \Delta} \text{trans}$$

Access Control Rules

$$\frac{\Sigma; \mathbb{M}, xS_{By}, yS_{Az}, xS_{Az}; \Gamma \Rightarrow \Delta}{\Sigma; \mathbb{M}, xS_{By}, yS_{Az}; \Gamma \Rightarrow \Delta} \text{s-I-SS} \quad \frac{\Sigma, y; \mathbb{M}, xC_{Ay}, xP_{Ay}; \Gamma \Rightarrow \Delta}{\Sigma; \mathbb{M}; \Gamma \Rightarrow \Delta} \text{s-C2P}_{y \text{ new}}$$

$$\frac{\Sigma; \mathbb{M}, xC_{By}, xC_{Ay}; \Gamma \Rightarrow \Delta \quad \Sigma, z; \mathbb{M}, xC_{By}, xS_{Az}, zC_{By}; \Gamma \Rightarrow \Delta}{\Sigma; \mathbb{M}, xC_{By}; \Gamma \Rightarrow \Delta} \text{s-del-C}_{z \text{ new}}$$

$$\frac{\Sigma; \mathbb{M}, xS_{Ay}, xR_{Ay}; \Gamma \Rightarrow \Delta}{\Sigma; \mathbb{M}, xS_{Ay}; \Gamma \Rightarrow \Delta} \text{s-RS}$$

Fig. 1. Seq-ACL⁺ Rules

Theorem 4 (Soundness of Seq-ACL⁺). *If a sequent $\Sigma; \mathbb{M}; \Gamma \Rightarrow \Delta$ is derivable then it is valid in the sense of Definition 4.*

Theorem 5 (Completeness of Seq-ACL⁺). *If a formula α is valid in ACL⁺ (i.e., $\models \alpha$), then $x; ; \Rightarrow x : \alpha$ is derivable in Seq-ACL⁺.*

Theorems 4 and 5 imply that ACL⁺ is semi-decidable because the rules of Figure 1 can be implemented backwards with iterative deepening to always find a proof of any provable formula.

6.1 Termination

Next, we propose several conditions on application of rules of the sequent calculus Seq-ACL⁺, which together ensure that a backward search in the calculus always terminates. The conditions are based on similar conditions in the work of Negri [19] for the unimodal case. Although the conditions are known to preserve completeness in the unimodal case, we do not know whether they preserve completeness in Seq-ACL⁺ also. We strongly suspect that this is the case and state this belief as an unproved conjecture. We do prove that *some* of our termination conditions preserve completeness of proof search.

The first source of non-termination in backward proof search is that the rules saysL, ratifiedL, CL, and PR may increase the complexity of sequents in a backward proof search. However, as the following (provable) Lemma shows, such “critical” rules can be applied in a controlled way. (Without loss of generality we assume that the root of each proof has the form $x; ; \Rightarrow x : \varphi$).

Lemma 2 (Controlled use of rules). *In each branch of a backward proof search, it is useless to: (1) apply CL on the same transition relation $x C_A y \in \mathbb{M}$ more than once, (2) apply PR on the same transition relation $x P_A y \in \mathbb{M}$ more than once, (3) apply rule χ for $\chi \in \{\text{mon-S, mon-R, mon-C, mon-P, sym, trans, s-I-SS, s-del-C, s-C2P, s-RS}\}$ on the same transition formula (or label as in s-RS) more than once.*

However, there are other reasons why a backward proof search may not terminate. In particular:

1. Interaction of the rule (trans) with \rightarrow L adds new accessible worlds, and we can build chains of accessible worlds on which \rightarrow L can be applied *ad infinitum*.
2. Application of rules s-del-C and s-C2P generates transition relations with new labels that can be used for repeated application of the same rules.

We propose to bound the number of such interactions using a counting argument, as in the work of Negri [19]. Let $\text{depth}(F)$ be the height of the parse tree of formula F .

Definition 5 (Label distance). *Given a sequent $\Sigma, \mathbb{M}, \Gamma \Rightarrow \Delta$ and two labels x and y such that $x \leq y \in \mathbb{M}$, we define the distance $d(x, y)$ between two labels as 0 when $x = y$ and n when $x \neq y$, where n is the length of the longest sequence of transitions in \mathbb{M} “connecting” the two labels, i.e., $x \overset{\sim}{\circ} x_1, x_1 \overset{\sim}{\circ} x_2, \dots, x_{n-1} \overset{\sim}{\circ} y$ where $\overset{\sim}{\circ} \in \{S_A, C_A, R_A, P_A, \leq\}$ (for any principal A). As an example, if $\{x \leq y, y C_A z, z P_A k, x S_A k\} \in \mathbb{M}$, then $d(x, k) = 3$.*

Conjecture 1 (Bounded application of rules). The following bounding heuristic preserves completeness of proof search. In any backward proof search starting with the root $x; \Rightarrow x : F$, for any label x_1 occurring in the search such that $d(x, x_1) > \text{depth}(F)$, it is useless to: (1) apply $\rightarrow L$ on a transition formula $x_1 \leq x_2$, (2) apply $s\text{-C2P}$ on the label x_1 , (3) apply $s\text{-del-C}$ on a transition formula $x_1 C_B x_2$.

If this conjecture holds, we easily obtain decidability for ACL^+ .

Conjecture 2 (Decidability). The logic ACL^+ is decidable.

A Prolog implementation of Seq-ACL^+ with the above termination conditions is available from our homepages.

7 Extending Seq-ACL^+ with Constructs for Subordination

The correspondence between semantic conditions and axioms allows us to modularly extend ACL^+ with new axioms, and new (corresponding) sequent calculus rules. As a specific case, we show here how we may extend the logic with new *subordination axioms* of any of the following forms, and obtain completeness with respect to the semantics. (In these axioms A and B are specific principals, not metavariables, but φ is a metavariable standing for all formulas.)

$$\begin{array}{ll}
\vdash A \text{ says } \varphi \rightarrow B \text{ says } \varphi & (\text{sub-S})_B^A \\
\vdash A \text{ ratified } \varphi \rightarrow B \text{ ratified } \varphi & (\text{sub-R})_B^A \\
\vdash \mathbf{P}_A \varphi \rightarrow \mathbf{P}_B \varphi & (\text{sub-P})_B^A \\
\vdash \mathbf{C}_A \varphi \rightarrow \mathbf{C}_B \varphi & (\text{sub-C})_B^A
\end{array}$$

We call these axioms subordination axioms because each axiom suggests that one of the two principals A and B is subordinate to the other. The first (second) axiom means that statements (ratifications) of A are echoed by B , so B is, in a sense, subordinate to A . The third (fourth) axiom means that if A has a permission (ability to control), then so does B , so B is more powerful than A .

Definition 6. *The semantic conditions on models corresponding to the axioms above are, respectively:*

$$\begin{array}{ll}
\forall x, y. (x S_B y \rightarrow x S_A y) & (\text{s-sub-S})_B^A \\
\forall x, y. (x R_B y \rightarrow x R_A y) & (\text{s-sub-R})_B^A \\
\forall x, y. (x P_A y \rightarrow x P_B y) & (\text{s-sub-P})_B^A \\
\forall x, y. (x C_B y \rightarrow x C_A y) & (\text{s-sub-C})_B^A
\end{array}$$

Corresponding access control rules for the sequent calculus are shown in Figure 2.

Lemma 3. *Extension of Seq-ACL^+ with any subset of the rules in Figure 2 preserves admissibility of cut. Further, the calculus is sound and complete with respect to intuitionistic models that satisfy the corresponding conditions from Definition 6.*

$$\begin{array}{c}
\frac{\Sigma; \mathbb{M}, xS_{Ay}, xS_{By}; \Gamma \Rightarrow \Delta}{\Sigma; \mathbb{M}, xS_{By}; \Gamma \Rightarrow \Delta} \text{s-sub-}S_B^A \\
\frac{\Sigma; \mathbb{M}, xP_{Ay}, xP_{By}; \Gamma \Rightarrow \Delta}{\Sigma; \mathbb{M}, xP_{Ay}; \Gamma \Rightarrow \Delta} \text{s-sub-}P_B^A \\
\frac{\Sigma; \mathbb{M}, xR_{Ay}, xR_{By}; \Gamma \Rightarrow \Delta}{\Sigma; \mathbb{M}, xR_{By}; \Gamma \Rightarrow \Delta} \text{s-sub-}R_B^A \\
\frac{\Sigma; \mathbb{M}, xC_{By}, xC_{Ay}; \Gamma \Rightarrow \Delta}{\Sigma; \mathbb{M}, xC_{By}; \Gamma \Rightarrow \Delta} \text{s-sub-}C_B^A
\end{array}$$

Fig. 2. Access Control Rules for Subordination

8 Related Work

The study of formal properties of says and other constructs in modal logic is a relatively new research trend. Prior work by the second author [10] adopts a modified version of constructive modal logic S4 called DTL_0 and shows how existing access control logics can be embedded (via translation) into DTL_0 . Other work [11] translates existing access control logics into S4 by relying on a slight simplification of Gödel’s translation from intuitionistic logic to S4, and extending it to formulas of the form A says φ . The first author has developed conditional logics as a general framework for modular sequent calculi for standard access control logics with the says connective [15,16]. Dinesh et al. [9] present an access control logic based on says and extended with obligation and permissions, but their treatment of permissions is different from ours and is closely tied to says. The use of canonical properties for access control axioms was first considered in [8] where standard access control axioms (e.g. (unit) and (hand-off)) are characterized in terms of first-order conditions on Kripke models.

The says modality also appears in several languages for writing access control policies, notably SecPAL [7] and DKAL [17]. But there are several differences in these languages and ACL^+ . For example, ACL^+ is propositional, whereas both SecPAL and DKAL have first-order quantification over principals and other objects, which is often useful to compact policy representation. However, these languages remove other features to maintain decidability: In both SecPAL and DKAL, the says modality can only be applied over atoms. In particular, the use of says over a disjunction is prohibited by both SecPAL and DKAL, although it may be useful in distributed scenarios where communication is not guaranteed. For instance, if the reference monitor knows that A says $(\varphi \vee \psi)$, but principal A is not available to verify which of φ or ψ it supports, it might still be possible to infer a useful fact from A says $(\varphi \vee \psi)$ alone. In both SecPAL and DKAL such a fact cannot be expressed and hence this situation cannot be modeled.

9 Conclusion

We have presented ACL^+ , a constructive multi-modal logic for access control that introduces three new modalities P_A (permission), C_A (control), and ratified (trusted statement) to fix practical problems in reasoning with policies using logic. The connectives of the logic are defined by a sound and complete Kripke semantics for ACL^+ together with a correspondence between conditions on models and the logic’s axioms. The semantics lead to $Seq\text{-}ACL^+$, a sound, complete, cut-free calculus for ACL^+ and a semi-decision procedure for it. Finally, ACL^+ can be extended with new axioms, as illustrated by examples of axioms for specific kinds of subordination among principals.

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